
Difference-frequency time scales for multitime PDEs

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Introduction

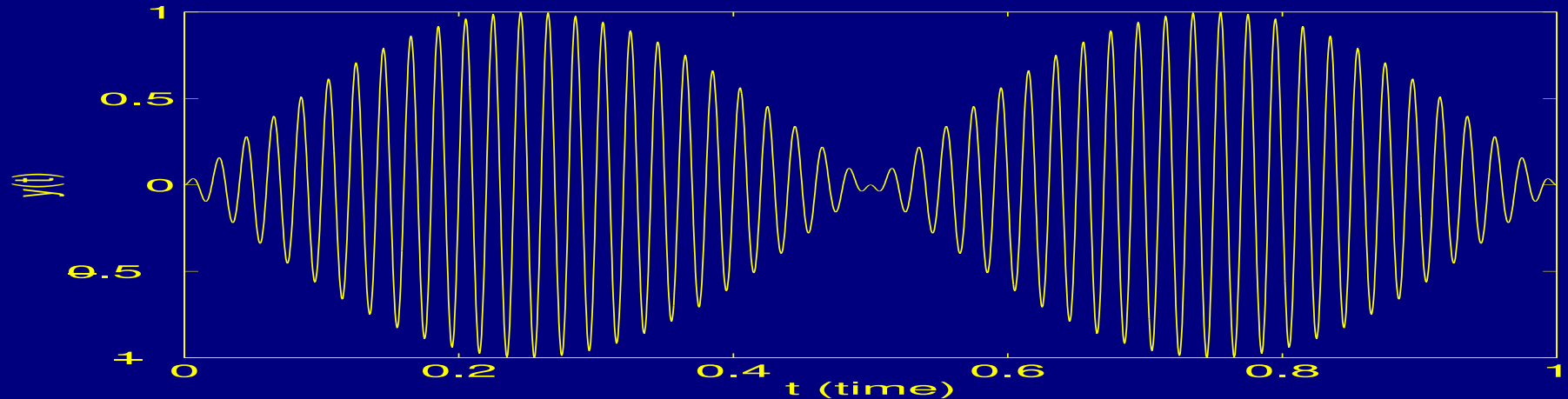
- The circuit DAE:

$$g(\dot{x}, x, t) = 0, \quad \text{or,} \quad \dot{q}(x) + f(x) + b(t) = 0$$

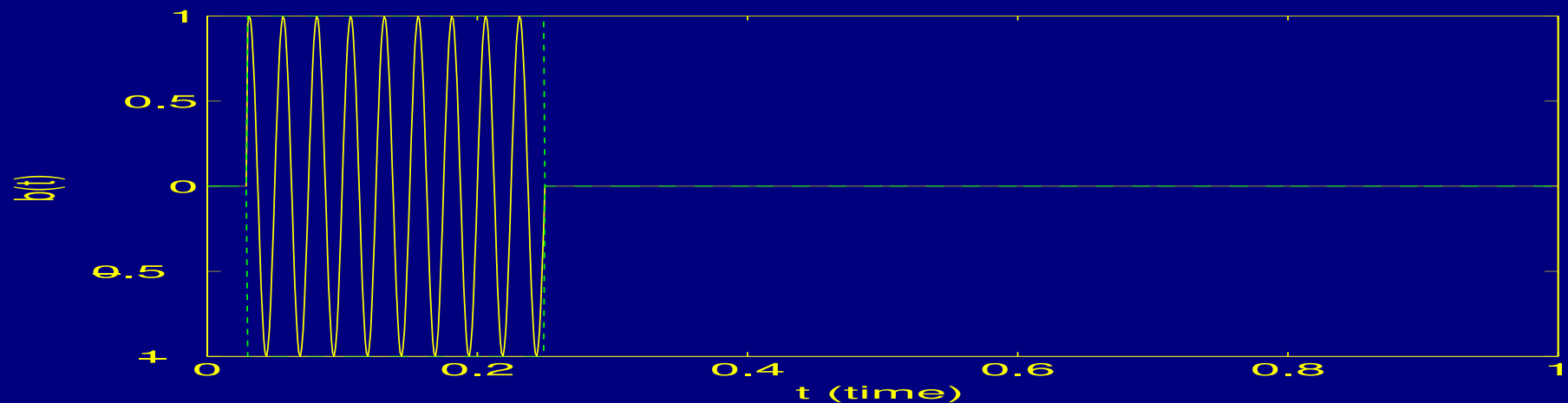
- The problem:
 - $b(t)$ is multi-tone, time scales widely separated
 - $f(\cdot)$, $q(\cdot)$ are strongly nonlinear
- ODE/DAE initial value solvers can take very long

Representing “multi-rate” signals

$$b(t) = \sin(2\pi 1t) \sin(2\pi 10^9 t) \quad \text{TD: } 10^{10} \text{ samples; FD: 2 harmonics}$$

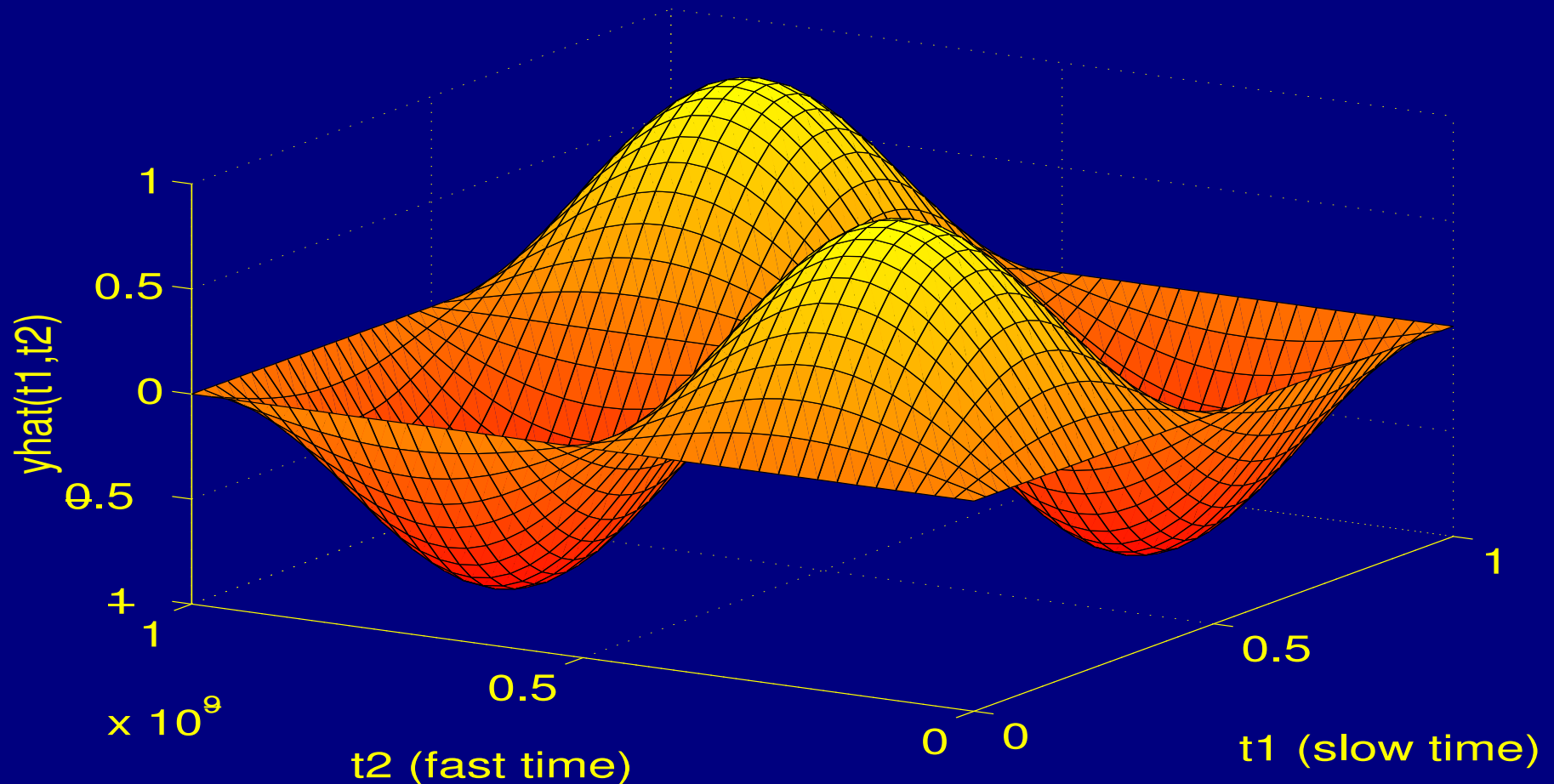


$$b(t) = \text{pulse}(1t) \sin(2\pi 10^9 t) \quad \text{TD: } 10^{10} \text{ samples; FD: } 10^n \text{ harmonics}$$



Two Artificial Time Scales

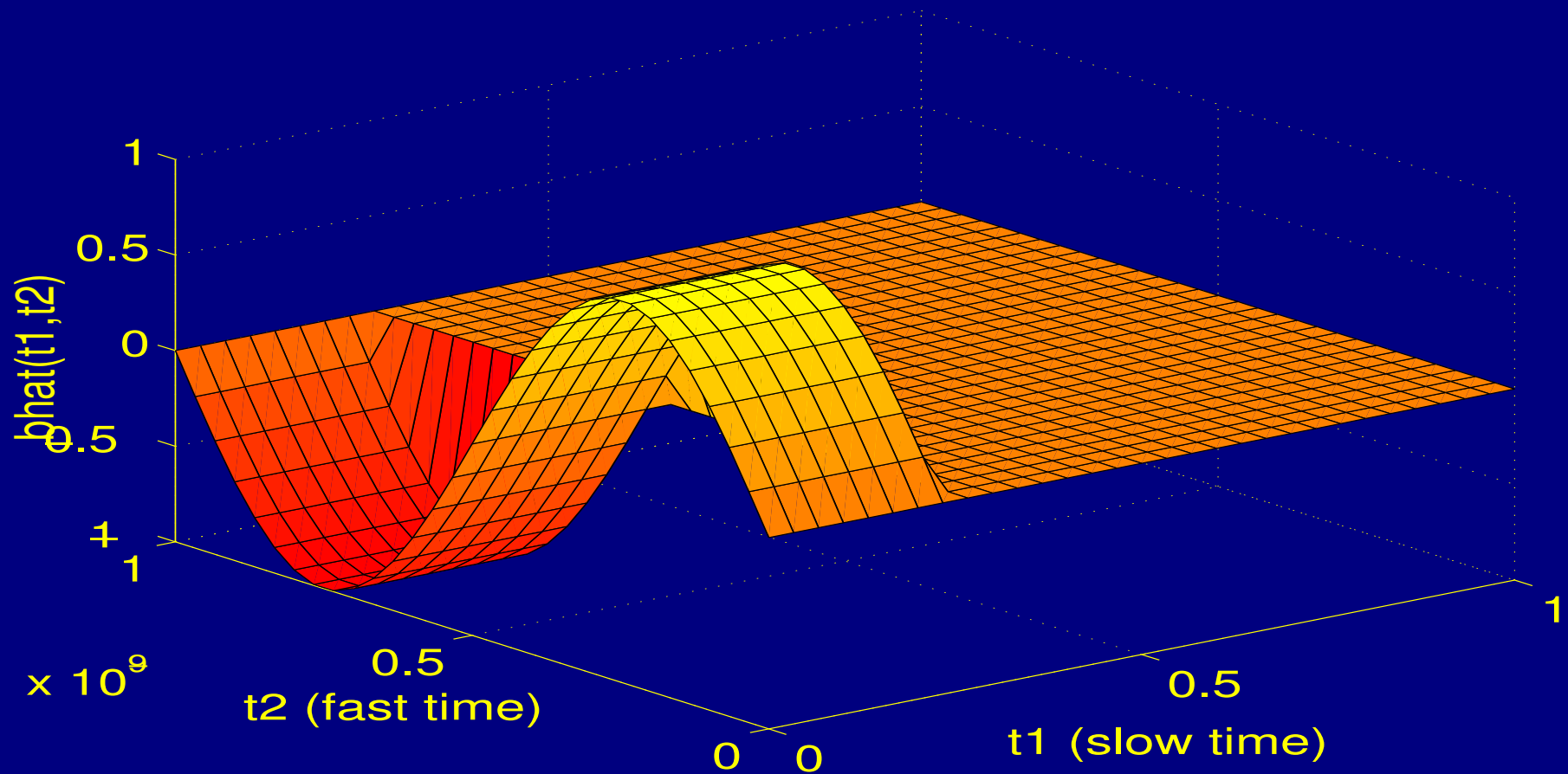
- Two time variables separate time scales



$$\hat{x}(t_1, t_2) = \sin(2\pi 1 t_1) \sin(2\pi 10^9 t_2) \quad x(t) = \hat{x}(t, t)$$

Two Artificial Time Scales

- “Strongly nonlinear” waveforms



$$\hat{b}(t_1, t_2) = \text{pulse}(1t_1) \sin(2\pi 10^9 t_2) \quad b(t) = \hat{b}(t, t)$$

The Multitime Partial Differential Equation (MPDE)

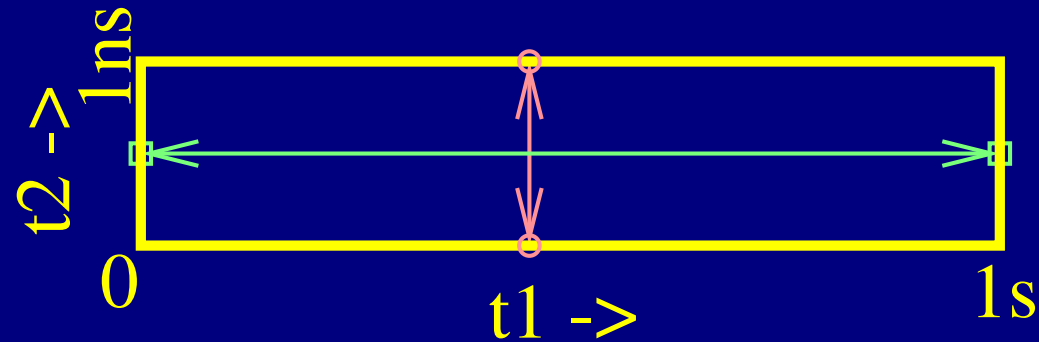
- Re-write DAE using multi-time variables

$$\boxed{\text{DAE}} \quad \dot{q}(x) + f(x) = b(t) \quad \rightsquigarrow \quad \boxed{\text{MPDE}} \quad \left(\frac{\partial}{\partial t_1} + \frac{\partial}{\partial t_2} \right) q(\hat{x}) + f(\hat{x}) = \hat{b}(t_1, t_2)$$

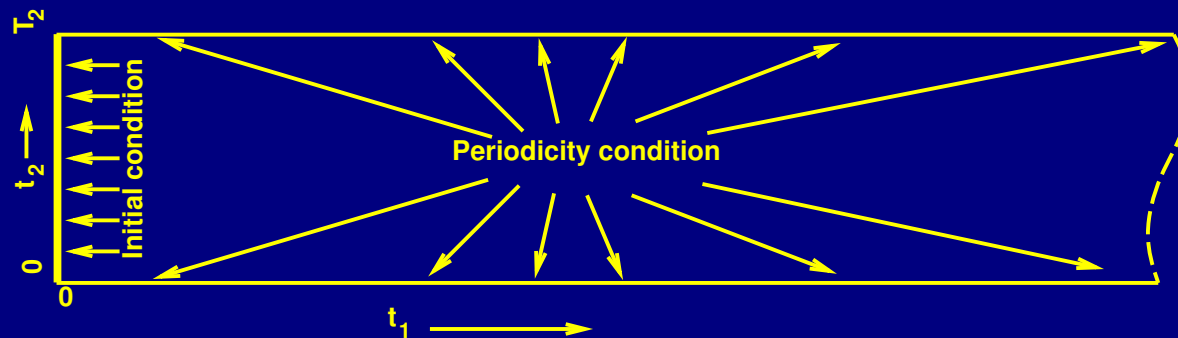
- $\hat{x}(t_1, t_2)$: vector of *multivariate* unknowns
- $\hat{b}(t_1, t_2)$: multivariate form of inputs
- MPDE solution \Rightarrow DAE solution
- $b(t) = \hat{b}(t, t) \Rightarrow x(t) = \hat{x}(t, t)$
- Key: solve for multivariate forms *directly*

Quasiperiodic/Envelope Solutions

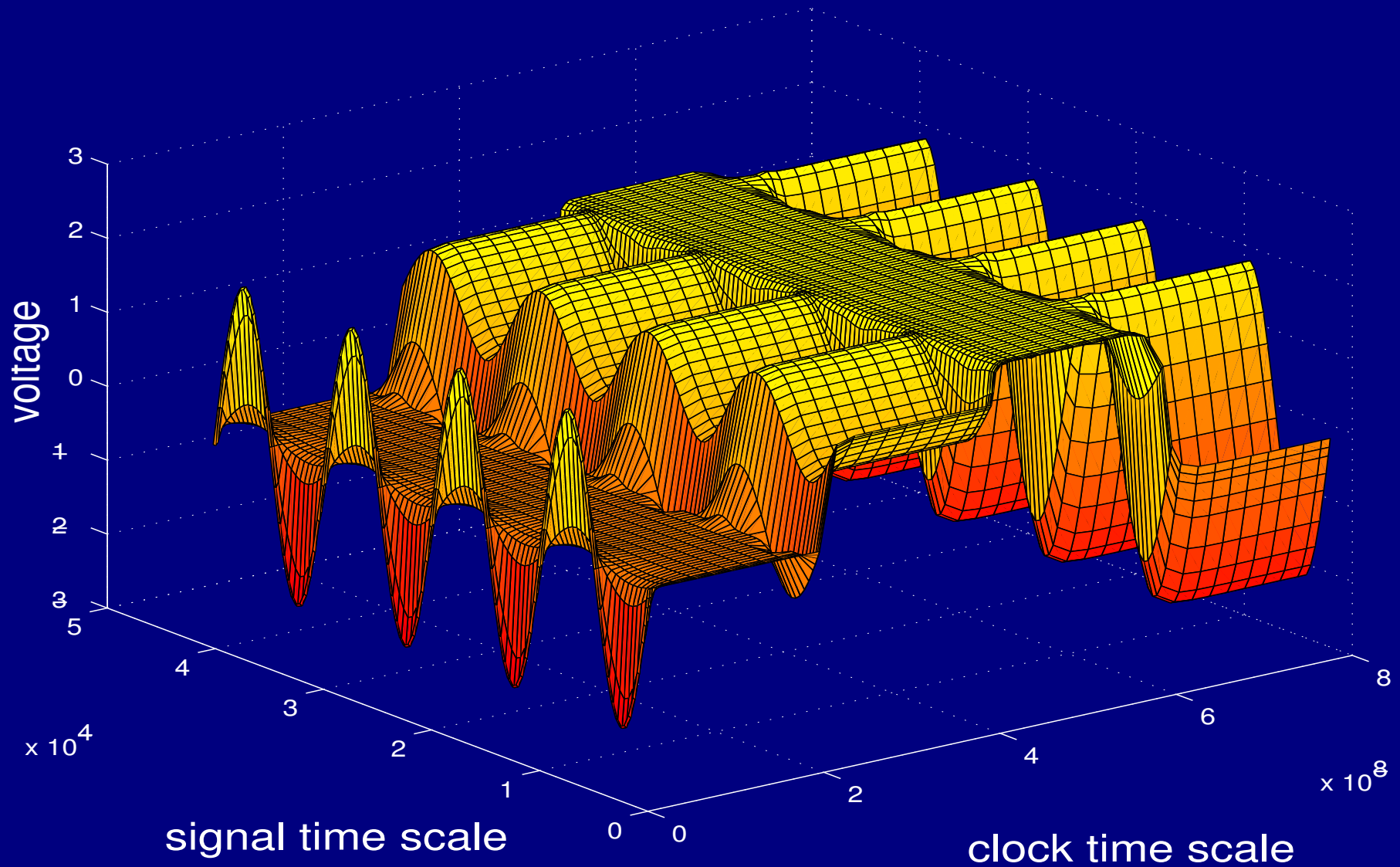
- Quasiperiodic: periodic boundary conditions
 - $\sin(2\pi 1 t_1) \text{pulse}(2\pi 10^9 t_2)$



- Envelope: mixed initial/periodic BCs
 - $a(t_1) \text{pulse}(2\pi 10^9 t_2)$

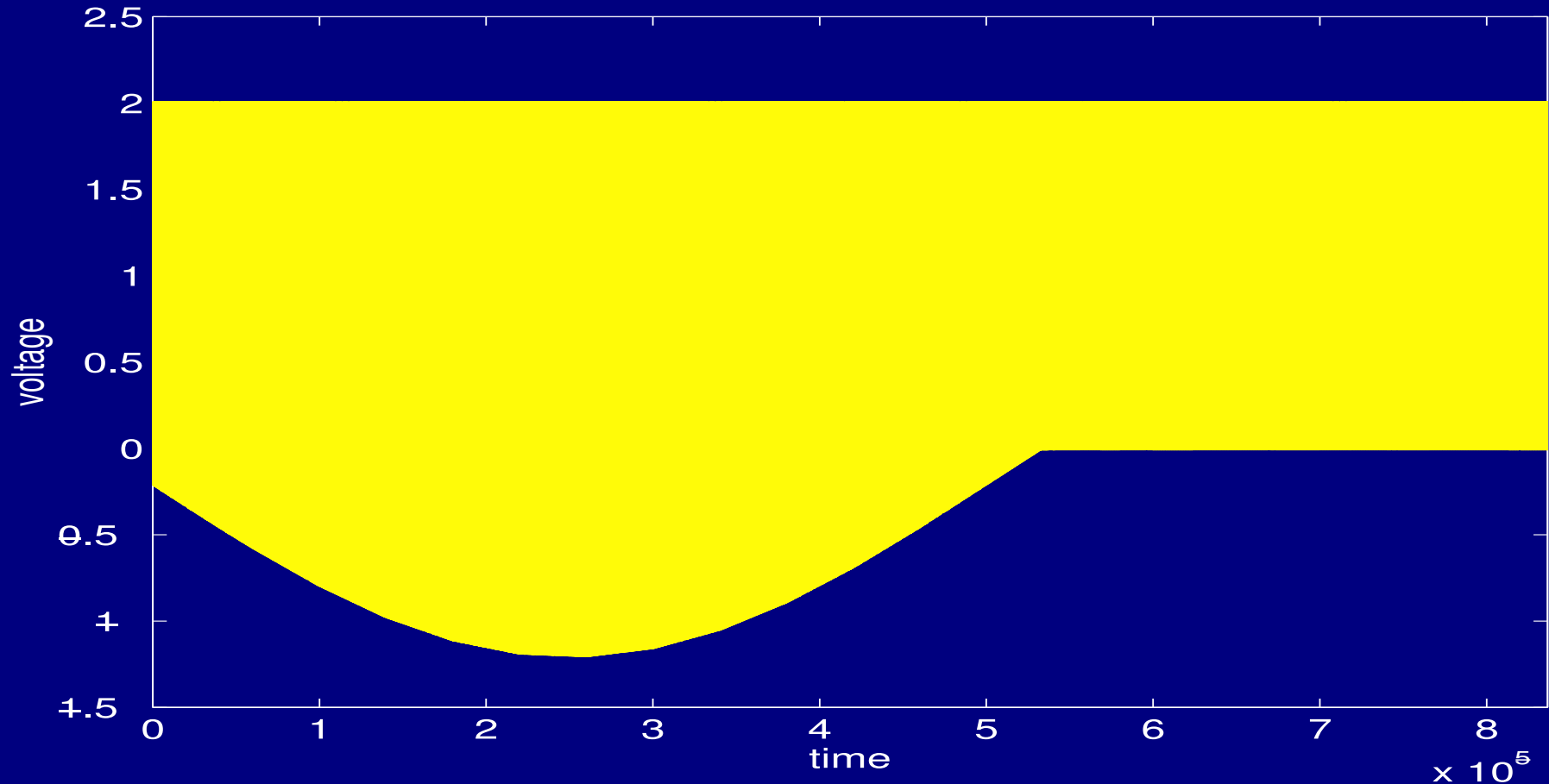


SC Integrator: Multi-Time Simulation

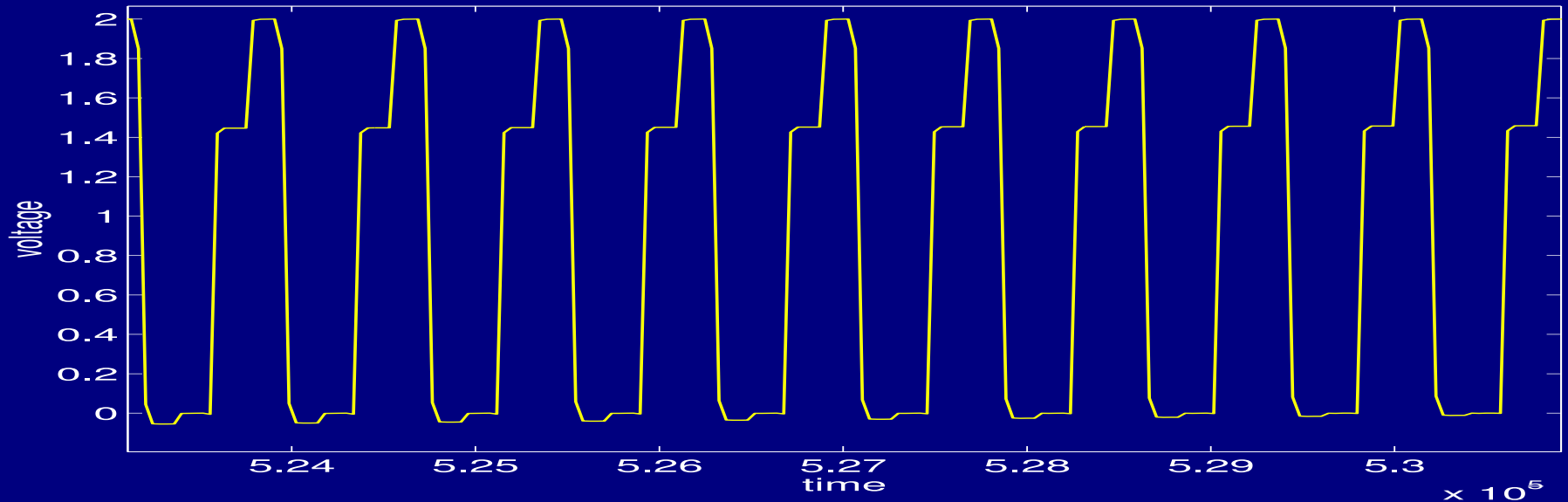
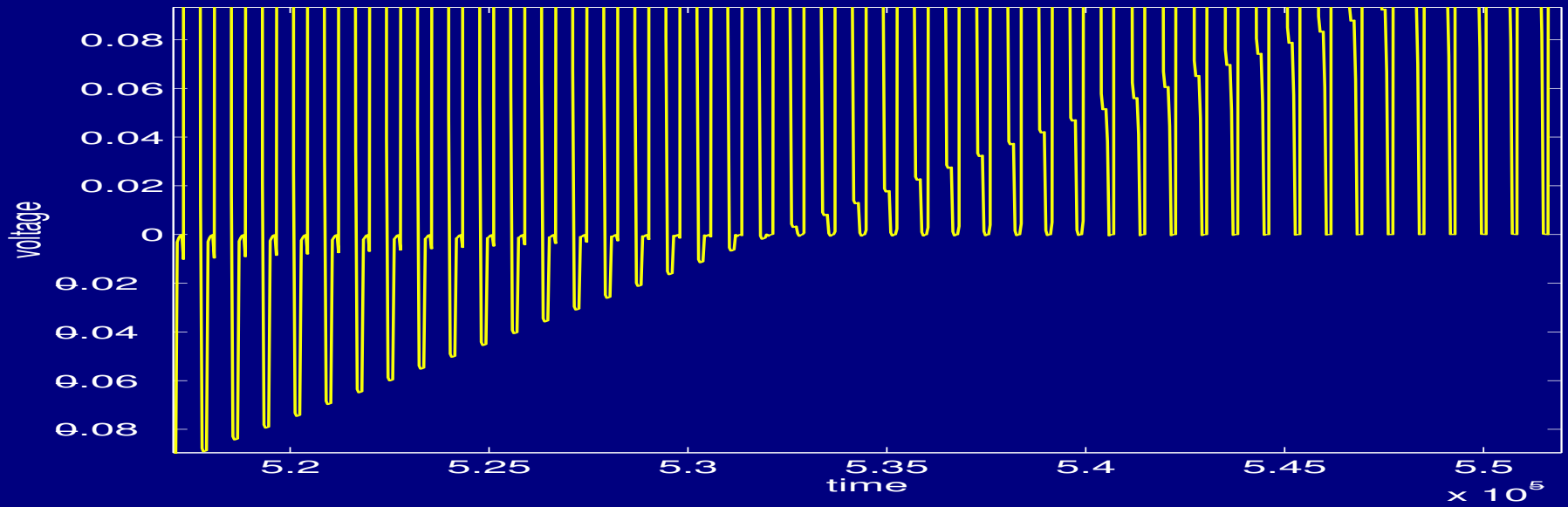


Switched-Capacitor Integrator

- Lossy balanced design; 350 MOSFETs
- clock: 12.8 MHz; test signal: 10 kHz



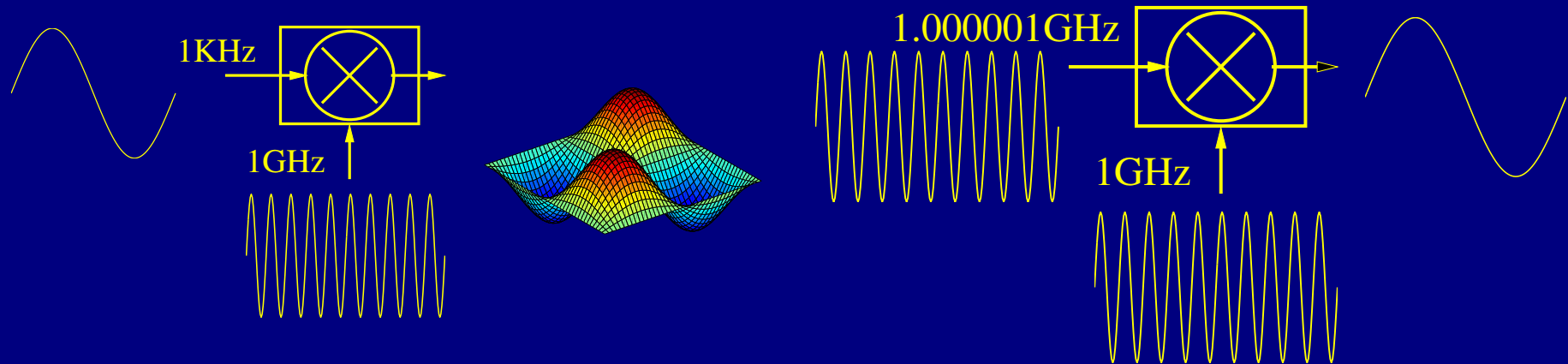
SC Integrator: transient detail



Development of multi-time PDE concepts

- Separate time scales for SHO perturbations: asymptotic expansions
- First mention of MPDE: Ngoya/Larchevèque
- Multitone HB derived from MPDE: Brachtendorf
- Time-domain/mixed/envelope methods for strongly nonlinear MPDE: R.
- MPDE methods for oscillators: Brachtendorf (startup); Narayan & R. (WaMPDE)
- MPDE for LTV/nonlinear macromodelling: R.
- Difference-frequency time scales

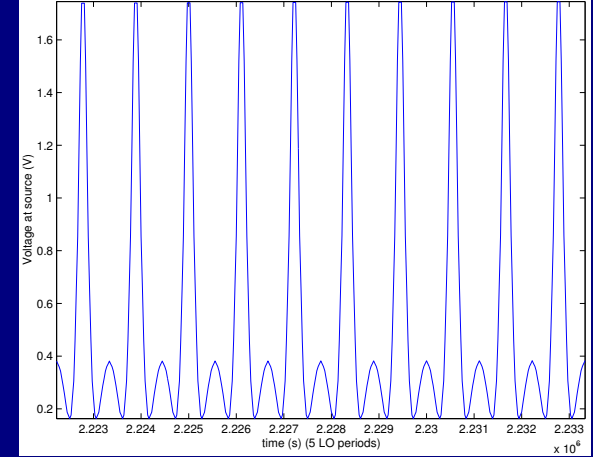
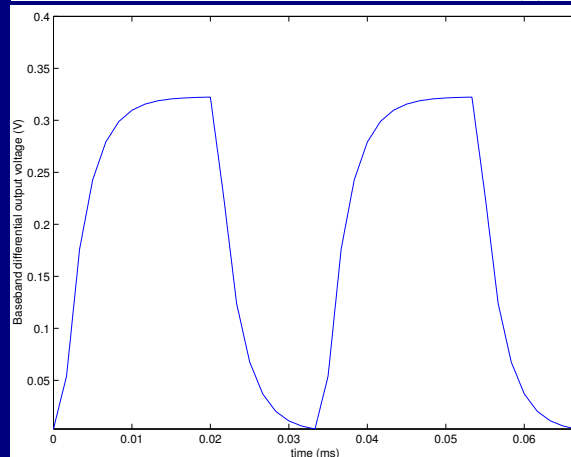
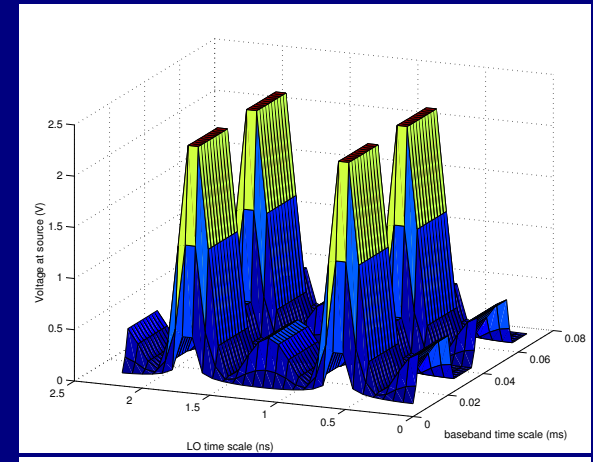
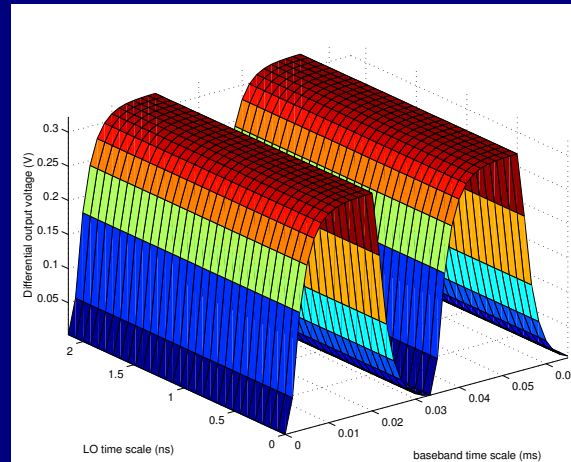
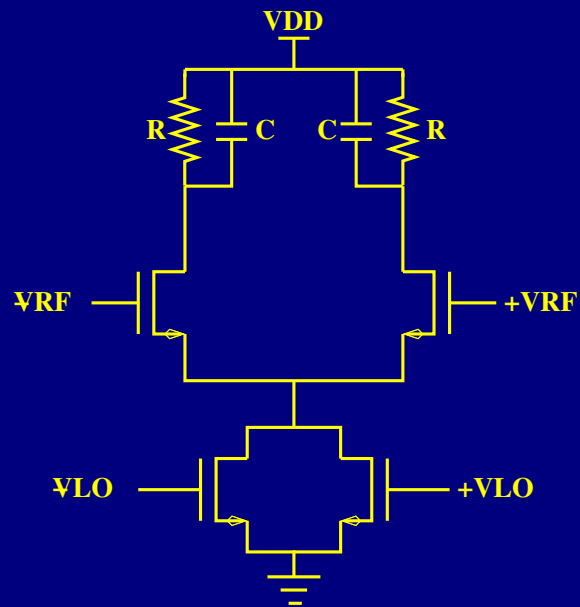
The Down-conversion Problem



- Up-conversion
- input specification: 1 slow, 1 fast time scale
- $\hat{x}(t_1, t_2) = \sin(10^3 t_1) \sin(10^9 t_2)$
- output envelope: along t_1

- Down-conversion
- input specification: two fast time scales
- $\hat{x}(t_1, t_2) = \sin((10^9 + 10^3)t_1) \sin(10^9 t_2)$
- output envelope: along neither t_1 nor t_2

LO-doubling downconversion mixer



LO=450MHz; 15kHz bitstream; 40x30 grid; prob-1 homotopy; speedup vs shooting: ~ 100

Conclusion and Directions

- Widely-separated timescales: DAEs \Rightarrow artificial-time PDEs
 - Unifying: HB, mixed F/T, envelope, ...
- Difference-frequency time scales
 - Slow envelope, including Fourier envelope (HB)
- New, little explored area
 - Import existing PDE techniques (*e.g.*, adaptive gridding)
 - Pre-conditioners
 - Surprises/opportunities remain in circuit simulation